

R16-PCM

16 Channel Telemetry for railway wheels

Including signal conditioning for strain gages

User Manual – DEMO



- Full- and half bridge
- Auto Zero Offset calibration
- 4V bridge Excitation
- 16 bit resolution
- Simultaneous sampling
- Sampling rate 16x 9500Hz
- Signal bandwidth: 16 x 0-3000Hz
- Software programmable
- Gain 125-250-500-1000-2000
- Inductive power transfer
- Wireless digital data transmission
- Output analog +/- 10V
- Digital data interface to PC (option)
- Waterproofed housing (IP65)

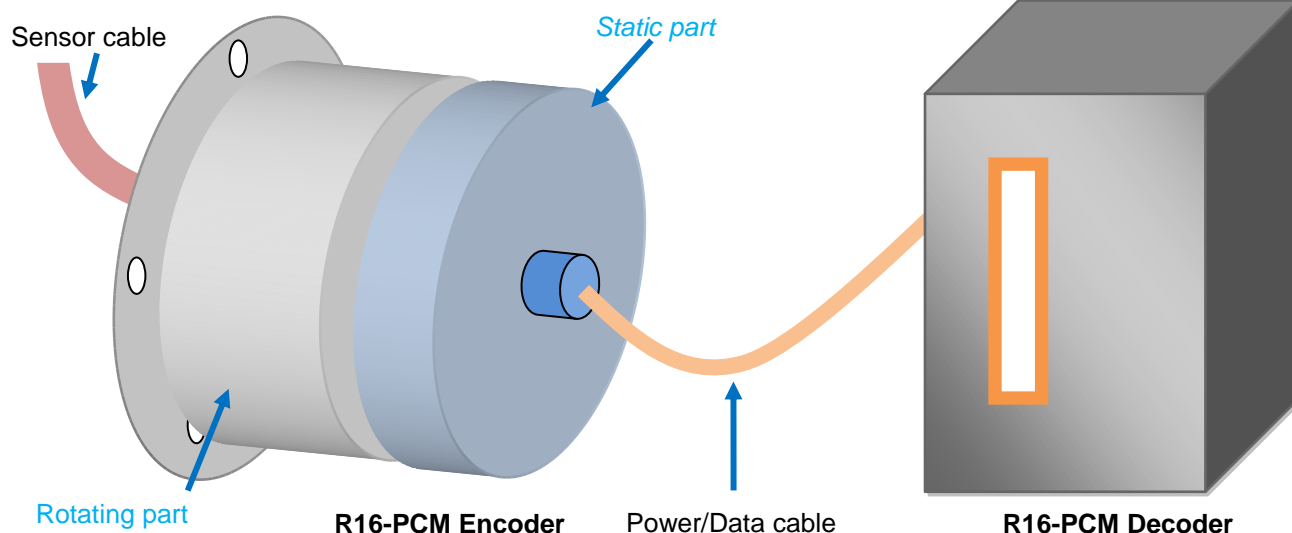
R16-PCM - Technical Data:



Encoder (Rotor Electronic)

Decoder

Number of channels:	16	Number of channels:	16
Sensor support	Strain gages full and half bridge $\geq 120\Omega$	Analog Output	+/-10V via 37-Sub-D connector
Excitation	4V for all channels	Digital Output	PCM serial (optional PCM interface for PC)
Gain	125-250-500-1000-2000 (selectable by software)		
Offset calibration	Automatically (Auto Zero)		
Antialiasing filter	5-pole Butterworth and 2-stages digital down sampling filter		
Band width	3000 Hz per channel	Band width	3000 Hz per channel
Sampling rate	9500 Hz per channel		
Resolution	16 bit ADC	DAC (digital to analog converting)	16 bit
Powering	Inductive	Powering	10-30V, 25 Watt
Data transmission	PCM digital infrared link	Data receiving	PCM digital twisted pair
Operating temperatures	-20 ... 80°C	Operating temperatures	-20 ... 70°C
RPM	Max. 3000		
Dimensions	100 diameter 110 Lengths (mm)	Dimensions	205 x 105 x 120 (mm)
Weight	1.2 kg	Weight	2.5 kg
Housing protection type	IP65	Housing protection type	IP54
Housing material	Aluminum anodized	Housing material	Aluminum anodized
Humidity	20...100%	Humidity	20 ... 80% (not condensing)
Shock	1000g	Shock	100g
Vibration	+/- 10g	Vibration	5g
Power/Data cable	Length up to 50m, 10m is standard (between Encoder /Decoder)	System accuracy	$\pm 0.25\%$ (without sensor)




Settings

Web interface address:
IP 192.168.0.110

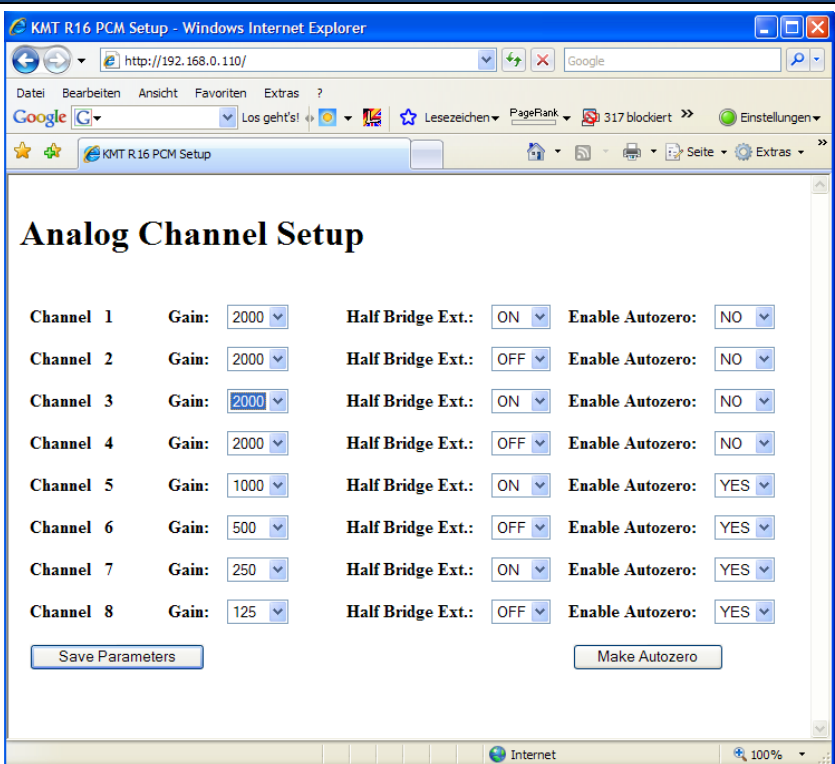
Settings:

Gain 125-250-500-1000-2000
Half- and full bridge
Auto Zero YES/NO

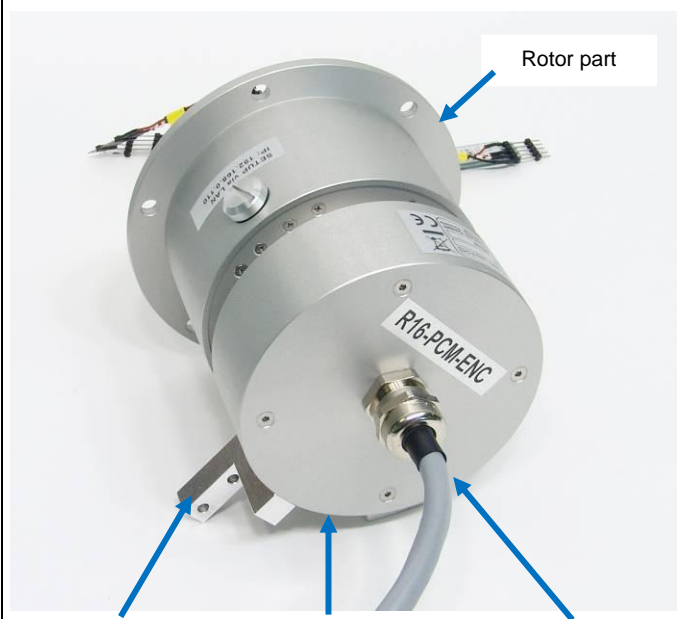


Programming connector

Programmable via web interface



Channel	Gain	Half Bridge Ext.	Enable Autozero
Channel 1	2000	ON	NO
Channel 2	2000	OFF	NO
Channel 3	2000	ON	NO
Channel 4	2000	OFF	NO
Channel 5	1000	ON	YES
Channel 6	500	OFF	YES
Channel 7	250	ON	YES
Channel 8	125	OFF	YES

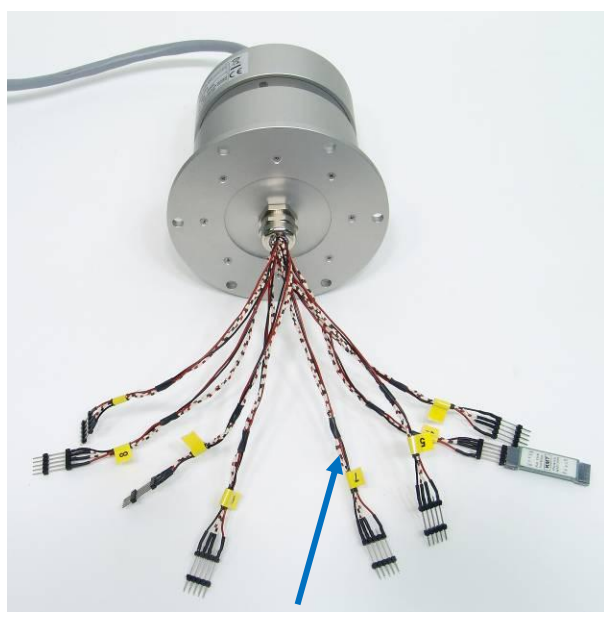


Rotor part

Stator arm for fixing

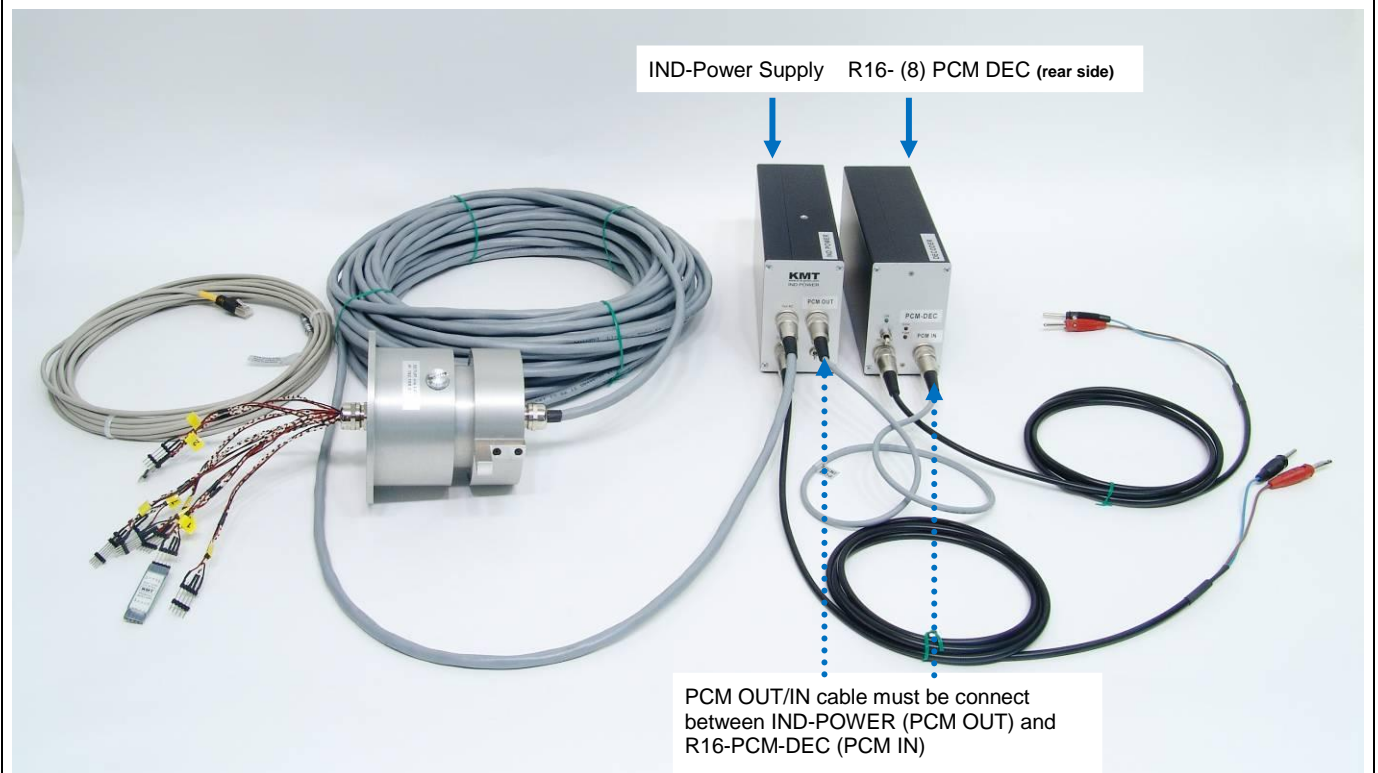
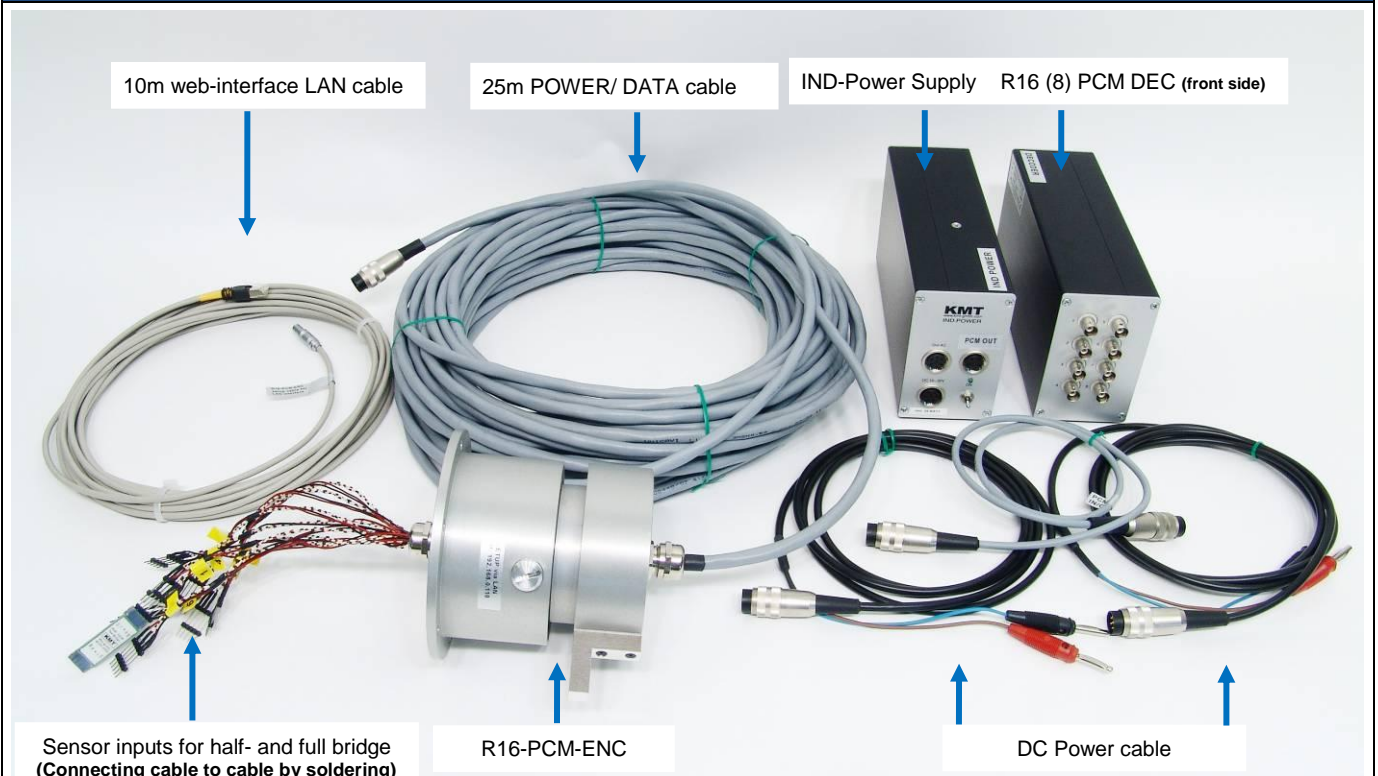
Stator part

Data / Power cable OUT



Sensor cable IN
(e.g. shows a 8 CH. version)

SET and cable connection of R16-PCM-ENC



Settings of R16-PCM-ENC Programmable via web interface



Web interface address of R16-PCM-ENC = IP 192.168.0.110

KMT R16 PCM Setup - Windows Internet Explorer

http://192.168.0.110/

Analog Channel Setup

ON for Half Bridge
OFF for Full Bridge

Channel	Gain	Half Bridge Ext.	Enable Autozero
Channel 1	Gain: 2000	Half Bridge Ext.: ON	Enable Autozero: NO
Channel 2	Gain: 2000	Half Bridge Ext.: OFF	Enable Autozero: NO
Channel 3	Gain: 2000	Half Bridge Ext.: ON	Enable Autozero: NO
Channel 4	Gain: 2000	Half Bridge Ext.: OFF	Enable Autozero: NO
Channel 5	Gain: 1000	Half Bridge Ext.: ON	Enable Autozero: YES
Channel 6	Gain: 500	Half Bridge Ext.: OFF	Enable Autozero: YES
Channel 7	Gain: 250	Half Bridge Ext.: ON	Enable Autozero: YES
Channel 8	Gain: 125	Half Bridge Ext.: OFF	Enable Autozero: YES

Save Parameters

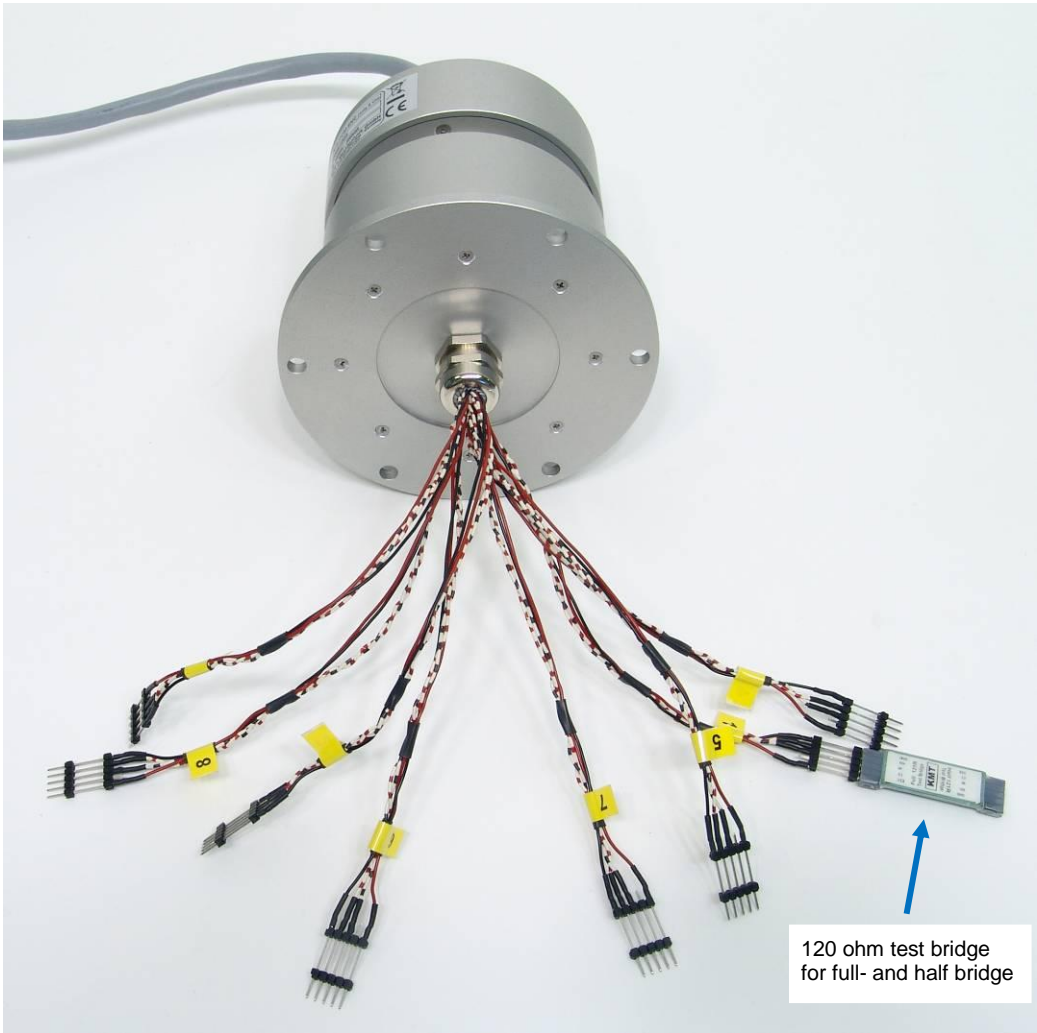
Make Autozero

Select Gain between 125-250-500-1000 and 2000

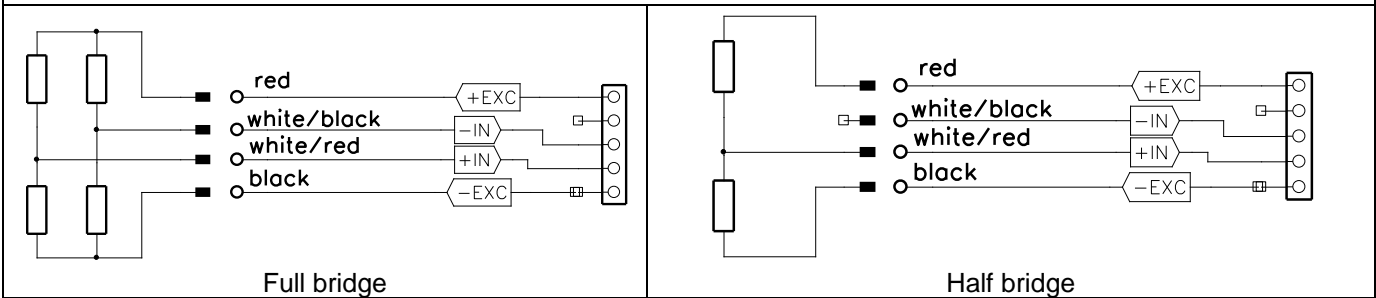
Autozero for CH1 YES or NO

Make Autozero at all channel instead channels with "Enable Autozero NO"

Pin sensor connection of R16-PCM-ENC



Sensor cable input (e.g. shows a 8 CH. version)



Dimensions of R16-PCM-ENC

